

Appendix for “Enforcing stationarity through the prior in vector autoregressions”

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Appendix

Forward mapping: VAR parameters to partial autocorrelations

This proceeds as described in Ansley and Newbold (1979). Using Cholesky factors in the matrix-square-roots below leads to the parameterization of Ansley and Kohn (1986), whilst using symmetric matrix-square-roots gives rise to the parameterization described in this paper.

The mapping from $(\Sigma, \Phi) \in \mathcal{S}_m^+ \times \mathcal{C}_{p,m}$ to $\{\Sigma, (P_1, \dots, P_p)\} \in \mathcal{S}_m^+ \times \mathcal{V}_m^p$, described in Ansley and Newbold (1979), proceeds in two main stages.

1. From (Σ, Φ) , compute the autocovariances $\Gamma_i = \text{Cov}(\mathbf{y}_t, \mathbf{y}_{t+i})$ ($i = 0, \dots, p$). $\Gamma_0, \dots, \Gamma_{p-1}$ can be found by representing the autoregression as a $\text{VAR}_{pm}(1)$ process and computing its stationary variance. The resulting discrete Lyapunov equation can be solved using vectorization and Kronecker product operators. The remaining autocovariance Γ_p can then be calculated using the Yule-Walker equations for the order p process. For further details, see, for example, Chapter 2 of Lütkepohl (2005).
2. From Φ and $(\Gamma_0, \dots, \Gamma_p)$ compute (P_1, \dots, P_p) :
 - (a) Initialize: construct $\Sigma_0 = \Sigma_0^* = \Gamma_0$ and then calculate the matrix-square-root factorizations, $\Sigma_0 = \Sigma_0^* = S_0 S_0^T = S_0^* S_0^{*T}$.
 - (b) Recursion: for $s = 0, \dots, p-1$:
 - (i) Compute $\phi_{s+1,s+1}$ and $\phi_{s+1,s+1}^*$ using

$$\begin{aligned}\phi_{s+1,s+1} &= (\Gamma_{s+1}^T - \phi_{s1}\Gamma_s^T - \dots - \phi_{ss}\Gamma_1^T) \Sigma_s^{*-1}, \\ \phi_{s+1,s+1}^* &= (\Gamma_{s+1} - \phi_{s1}^*\Gamma_s - \dots - \phi_{ss}^*\Gamma_1) \Sigma_s^{-1},\end{aligned}$$

where it is understood that when $s = 0$, these expressions simplify to $\phi_{11} = \Gamma_1^T \Sigma_0^{*-1} = \Gamma_1^T \Gamma_0^{-1}$, $\phi_{11}^* = \Gamma_1 \Gamma_0^{-1}$.

- (ii) If $s > 0$, for $i = 1, \dots, s$, compute $\phi_{s+1,i}$ and $\phi_{s+1,i}^*$ using

$$\phi_{s+1,i} = \phi_{si} - \phi_{s+1,s+1}\phi_{s,s-i+1}^*, \quad \phi_{s+1,i}^* = \phi_{si}^* - \phi_{s+1,s+1}^*\phi_{s,s-i+1}.$$

(iii) Compute P_{s+1} using one of

$$P_{s+1} = S_s^{-1} \phi_{s+1,s+1} S_s^*, \quad P_{s+1} = (S_s^{*-1} \phi_{s+1,s+1}^* S_s)^T.$$

(iv) If $s < p-1$, compute Σ_{s+1} and Σ_{s+1}^* using

$$\begin{aligned} \Sigma_{s+1} &= \Gamma_0 - \phi_{s+1,1} \Gamma_1 - \cdots - \phi_{s+1,s+1} \Gamma_{s+1}, \\ \Sigma_{s+1}^* &= \Gamma_0 - \phi_{s+1,1}^* \Gamma_1^T - \cdots - \phi_{s+1,s+1}^* \Gamma_{s+1}^T, \end{aligned}$$

then calculate the matrix-square-roots, $\Sigma_{s+1} = S_{s+1} S_{s+1}^T$, $\Sigma_{s+1}^* = S_{s+1}^* S_{s+1}^{*T}$.

Reverse mapping: partial autocorrelations to VAR parameters

The inverse mapping from $\{\Sigma, (P_1, \dots, P_p)\} \in \mathcal{S}_m^+ \times \mathcal{V}_m^p$ to $(\Sigma, \Phi) \in \mathcal{S}_m^+ \times \mathcal{C}_{p,m}$, comprises two recursions; the first is new and the second is based on Lemma 2.1 of Ansley and Kohn (1986).

1. From $\{\Sigma, (P_1, \dots, P_p)\}$ compute the stationary variance matrix Γ_0 :

- (a) Initialize: let $\Sigma_p = \Sigma$ with corresponding matrix-square-root factorization, $\Sigma_p = S_p S_p^T$.
- (b) Recursion: for $s = p-1, \dots, 0$ construct the symmetric (or lower triangular) matrix S_s such that

$$\Sigma_{s+1} = S_s (I_m - P_{s+1} P_{s+1}^T) S_s^T,$$

then compute $\Sigma_s = S_s S_s^T$.

- (c) Output: take $\Gamma_0 = \Sigma_0$.

2. From (P_1, \dots, P_p) and Γ_0 compute the matrices in Φ :

- (a) Initialize: let $\Sigma_0 = \Sigma_0^* = \Gamma_0$ with corresponding matrix-square-root factorization, $\Sigma_0 = \Sigma_0^* = S_0 S_0^T = S_0^* S_0^{*T}$.
- (b) Recursion: for $s = 0, \dots, p-1$:
 - (i) Compute $\phi_{s+1,s+1}$ and $\phi_{s+1,s+1}^*$ using

$$\phi_{s+1,s+1} = S_s P_{s+1} S_s^{*-1}, \quad \phi_{s+1,s+1}^* = S_s^* P_{s+1}^T S_s^{-1}.$$

- (ii) If $s > 0$, for $i = 1, \dots, s$, compute $\phi_{s+1,i}$ and $\phi_{s+1,i}^*$ using

$$\phi_{s+1,i} = \phi_{si} - \phi_{s+1,s+1} \phi_{s,s-i+1}^*, \quad \phi_{s+1,i}^* = \phi_{si}^* - \phi_{s+1,s+1}^* \phi_{s,s-i+1}.$$

- (iii) Compute Σ_{s+1} and Σ_{s+1}^* using

$$\Sigma_{s+1} = \Sigma_s - \phi_{s+1,s+1} \Sigma_s^* \phi_{s+1,s+1}^T, \quad \Sigma_{s+1}^* = \Sigma_s^* - \phi_{s+1,s+1}^* \Sigma_s \phi_{s+1,s+1}^T,$$

then calculate the matrix-square-roots, $\Sigma_{s+1} = S_{s+1} S_{s+1}^T$ and $\Sigma_{s+1}^* = S_{s+1}^* S_{s+1}^{*T}$.

- (iv) Compute Γ_{s+1} using

$$\Gamma_{s+1}^T = \phi_{s+1,s+1} \Sigma_s^* + \phi_{s1} \Gamma_s^T + \cdots + \phi_{ss} \Gamma_1^T.$$

- (c) Output: take $\phi_i = \phi_{pi}$ ($i = 1, \dots, p$). By construction, $\Sigma = \Sigma_p$.