Supplemental material for Bureerat and Sleesongsom, "Constraint Handling Technique for Four-Bar Linkage Path Generation Using Self-Adaptive Teaching-Learning Based Optimization with a Diversity Archive", Engineering Optimization, 2020.

Appendix

A. Algorithm 1. Function evaluation (with/without prescribed timing)

<u>Input</u> $\mathbf{x} = \{ r_1, r_2, r_3, r_4, r_{px}, r_{py}, \theta_0, x_{02}, y_{02}, \theta_i^i \}$

<u>Output</u> f, **x** and constraints

Evaluate constraints

Step 1 If the optimization problem is the without-prescribe-timing problem and if θ

 i_2 cannot fulfil constraint (3.2), activate Algorithm 2 to reassign the angle values.

Step 2 If constraints (3.3)-(3.4) are infeasible, activate the technique to reassign link lengths

lengths.

Position analysis and function evaluation

Step 1 Otherwise, solving Equations (2-3) for all values of θ_2 and solving Equation

(1) for \mathbf{r}_p at each θ_2 .

Step 2 Compute the objective function values and constraints according to Equation (3.1)-(3.5).

B. Algorithm 2: A reassigning technique for timing constraint

<u>Input</u> infeasible **x** at elements $\theta_2^i, \theta_2^{i+1}, ..., \theta_2^N$

<u>Output</u> feasible **x** at elements $\theta_2^i, \theta_2^{i+1}, ..., \theta_2^N$

Generate a set of uniform random numbers $\{\alpha_1, \dots, \alpha_N\}, \alpha_i \in (0, 1).$

If $(\alpha_2 + \ldots + \alpha_N) \ge 2\pi$, scale them down and modify their values as:

```
For i = 2 to N

Generate \alpha_i = 1.99 \pi \alpha_i / (\alpha_2 + ... + \alpha_N)

End

For i = 1 to N

Step 1 If i = 1, \theta_2^i = \alpha_1.

Step 2 Otherwise, \theta_2^i = \theta_2^{i-1} + \alpha_i.

End
```

C. Algorithm 3: Repairing the Grashof's criterion constraint.

```
<u>Input</u> infeasible {r_1, r_2, r_3, r_4}

<u>Output</u> feasible {r_1, r_2, r_3, r_4}

Step 1 Generate a set of uniform random numbers {\delta_1, \delta_2, \delta_3}, \delta_i \in (0,1).

Step 2 If 2\delta_3 \ge \delta_1

Step 3 Assign values

S_1 = \delta_1

S_2 = 2\delta_3

S_3 = 2\delta_3 + \delta_2

S_4 = 2\delta_3 + \delta_2 + \delta_1

Step 3 If max(S_1, S_2, S_3, S_4) > 1, compute S_i = S_i/2 and compute step (2) until

max(S_1, S_2, S_3, S_4) < 1

Step 4 Compute r_i = r_{min} + (r_{max} - r_{min})S_i for i = 1, ..., 4.
```

D. Algorithm 4 Procedure of ATLBO-DA

<u>Input:</u> maximum number of generations (n_{it}) , population size (n_P)

Output : **x**^{best}, *f*^{best}

Initialization:

Step 0.1 Generate n_p initial students $\{\mathbf{x}^i\}$ and perform function evaluations $\{f^i\}$.

Step 0.2 Initiate four 1×2 matrices, TRR_Success, TRR_Fail, LRR_Success and

LRR_Fail, whose all elements are set to be ones.

Main procedure

Step 1 While (the termination conditions are not met) do

{*Teacher Phase*}

Step 2 Calculate the mean position of solutions $\{\mathbf{x}^i\}$ written as \mathbf{M}_{avg} .

Step 3 Calculate the probabilities of selecting the intervals for T_{RR} using (18).

Step 4 For i=1 to n_P

Step 4.1 Perform roulette wheel selection with PTRR_j.

Step 4.1.1 If j = 1 is selected, $T_{RR} = 0.4 + 0.1$ rand is sampled.

Step 4.1.2 Else, if j = 2 is selected, $T_{RR} = 0.5 + 0.1$ rand is sampled.

Step 4.2 Generate $P_r = rand$ and select a teacher.

Step 4.2.1 If $P_r \leq T_{RR}$, set the best solution as a teacher \mathbf{M}_{best} .

Step 4.2.2 Else, if $P_r > T_{RR}$, randomly select a solution in A_D and set it as a teacher M_{best} .

Step 4.3 Create \mathbf{x}^{i}_{new} using (10 – 12) and perform function evaluation.

Step 4.3.1 If \mathbf{x}^{i}_{new} is better than \mathbf{x}^{i} , add 1 point to the *j*-th element of *TRR_Success*.

Step 4.3.2 Else, add 1 point to the *j*-th element of *TRR_Fail*.

Step 5 Replace $\{\mathbf{x}^i\}$ by n_P best solutions from $\{\mathbf{x}^i\} \cup \{\mathbf{x}^i_{new}\}$.

{Learning Phase}

Step 6 Calculate the probabilities of selecting the intervals for L_{RR} similar to that

for T_{RR} in step 3. $PTRR_{j} = \frac{LRR_Success_{j}}{LRR_Success_{j} + LRR_Fail_{j}}$

Step 7 For i=1 to n_P

Step 7.1 Perform roulette wheel selection with PLRR_j.

Step 7.1.1 If j = 1 is selected, $L_{RR} = 0.4 + 0.1 rand$ is sampled.

Step 7.1.2 Else, if j = 2 is selected, $T_{RR} = 0.5 + 0.1$ rand is sampled.

Step 7.2 Generate $P_r = rand$.

Step 7.2.1 If $P_r \leq L_{RR}$, create \mathbf{x}^i_{new} using two-student learning and perform function evaluation.

Step 7.2.2 Else, create \mathbf{x}^{i}_{new} using three-student learning and perform function evaluation.

Step 7.3 Update LRR_Success and LRR_Fail.

Step 7.3.1 If \mathbf{x}^{i}_{new} is better than \mathbf{x}^{i} , add 1 point to the *j*-th element of

LRR_Success.

Step 7.3.2 Else, add 1 point to the *j*-th element of *LRR_Fail*.

Step 8 Replace $\{\mathbf{x}^i\}$ by n_P best solutions from $\{\mathbf{x}^i\} \cup \{\mathbf{x}^i_{new}\}$. Calculate the

objective function value of \mathbf{x}^{i}_{new} .

Step 9 Update the diversity archive with the non-dominated solutions obtained

from $\{\mathbf{x}^i\}_{\text{old}} \cup \{\mathbf{x}^i\}_{\text{new}}$.

Step 10 End While